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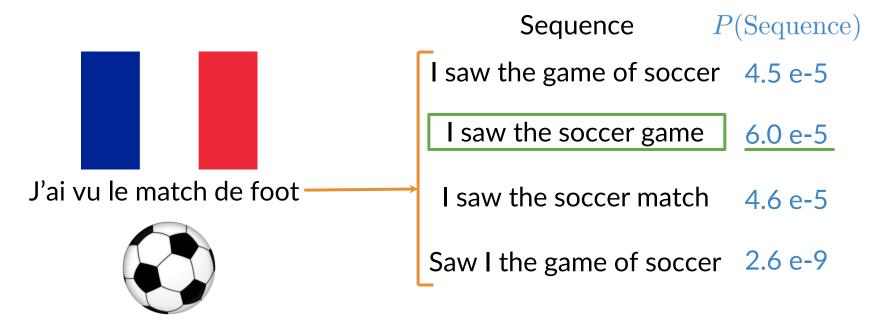
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# Traditional Language models

#### Traditional Language Models



#### N-grams

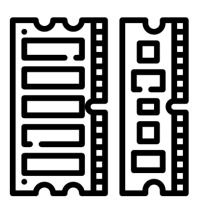
$$P(w_2|w_1) = \frac{\operatorname{count}(w_1, w_2)}{\operatorname{count}(w_1)} \longrightarrow \operatorname{Bigrams}$$

$$P(w_3|w_1, w_2) = \frac{\operatorname{count}(w_1, w_2, w_3)}{\operatorname{count}(w_1, w_2)} \longrightarrow \operatorname{Trigrams}$$

$$P(w_1, w_2, w_3) = P(w_1) \times P(w_2|w_1) \times P(w_3|w_2)$$

- Large N-grams to capture dependencies between distant words
- Need a lot of space and RAM

- N-grams consume a lot of memory
- Different types of RNNs are the preferred alternative

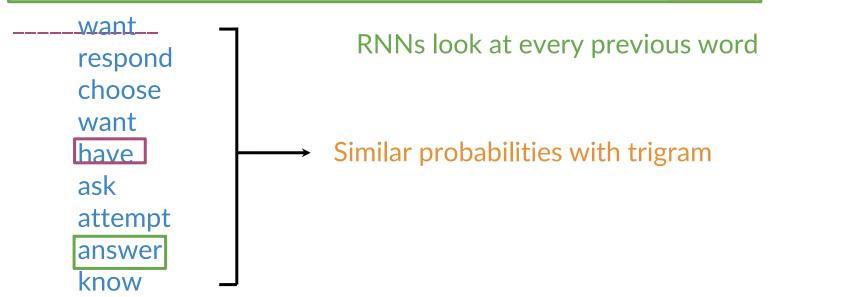




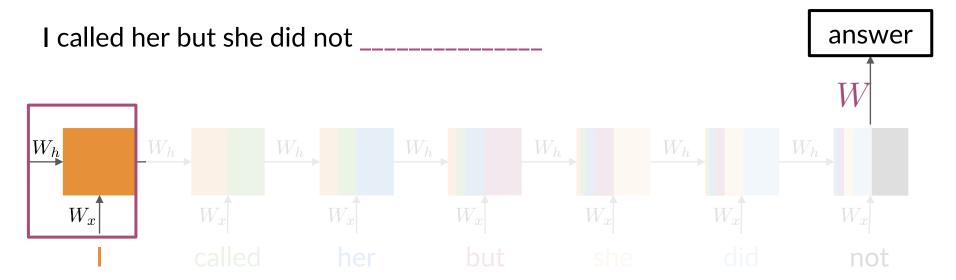
### Recurrent Neural Networks

#### Advantages of RNNs

Nour was supposed to study with me. I called her but she did not ahawer

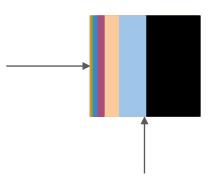


#### **RNNs Basic Structure**



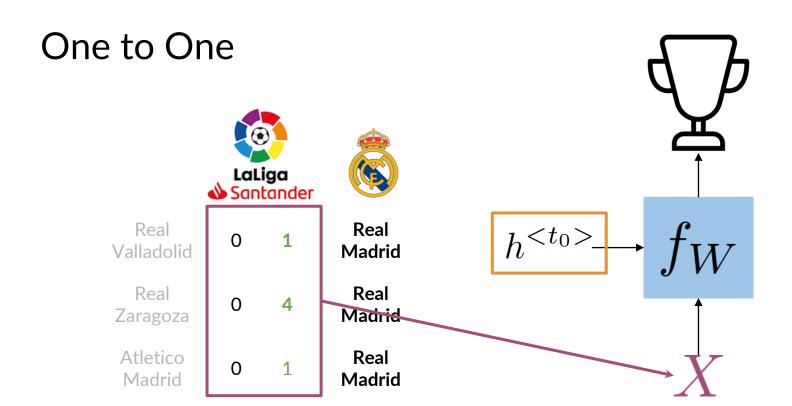
Learnable parameters

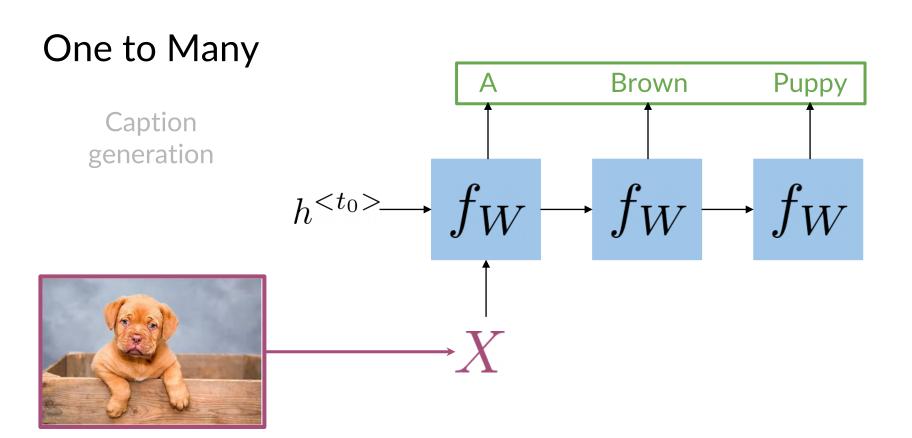
- RNNs model relationships among distant words
- In RNNs a lot of computations share parameters

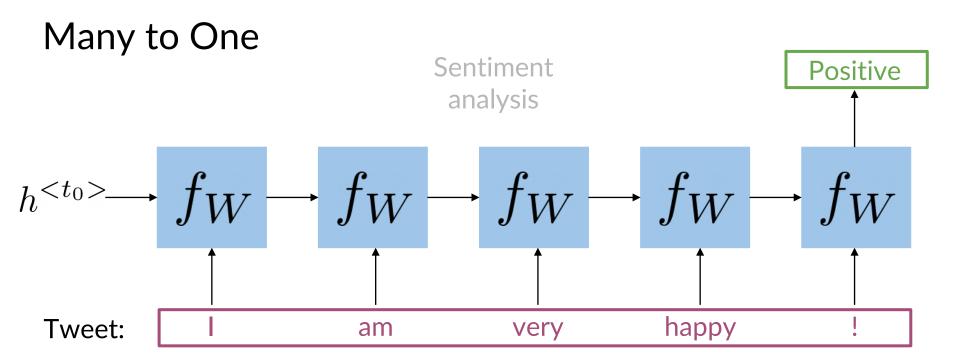




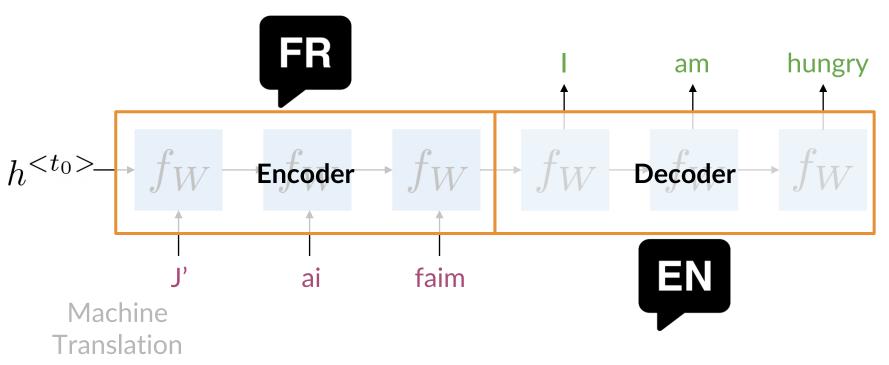
## Applications of RNNs







#### Many to Many



- RNNs can be implemented for a variety of NLP tasks
- Applications include Machine translation and caption generation





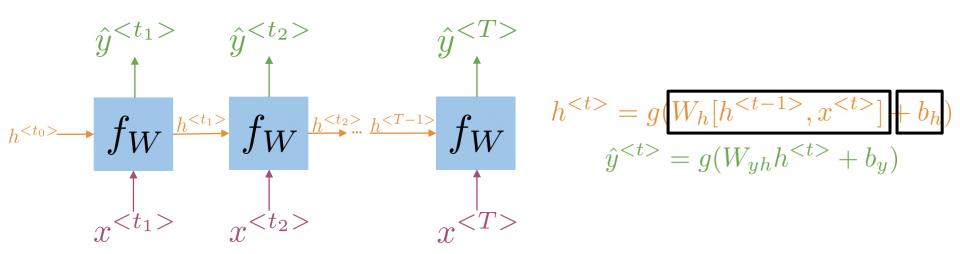
# Math in Simple RNNs

#### Outline

- How RNNs propagate information (Through time!)
- How RNNs make predictions

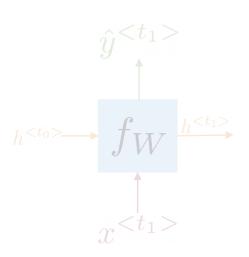


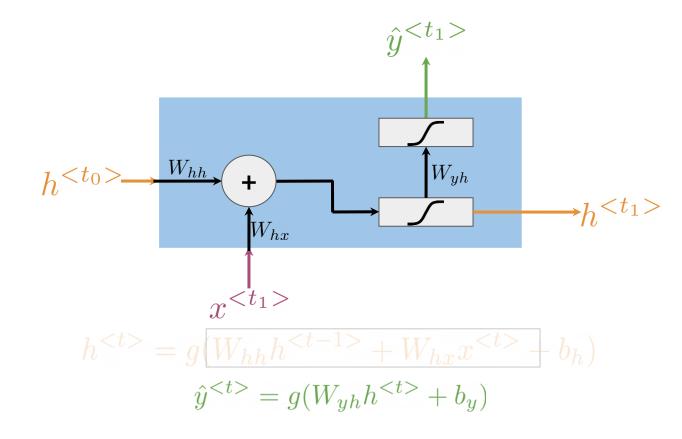
#### A Vanilla RNN



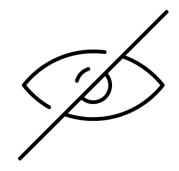
$$h^{< t>} = g(W_{hh}h^{< t-1>} + W_{hx}x^{< t>} + b_h)$$

#### A Vanilla RNN





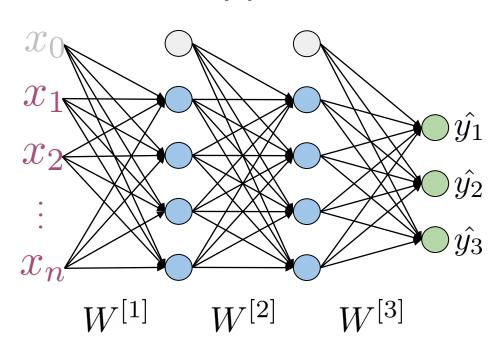
- Hidden states propagate information through time
- Basic recurrent units have two inputs at each time:  $h^{< t-1>}$   $x^{< t>}$





## Cost Function for RNNs

#### **Cross Entropy Loss**

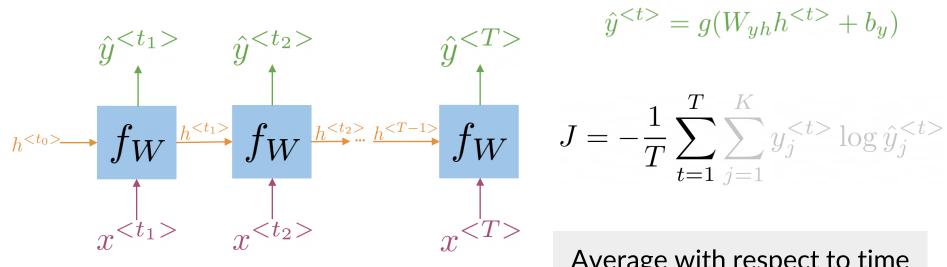


K - classes or possibilities

$$J = -\sum_{j=1}^{K} y_j \log \hat{y}_j$$

Looking at a single example (x, y)

#### Cross Entropy Loss



$$h^{} = g(W_h[h^{}, x^{}] + b_h)$$
$$\hat{y}^{} = g(W_{yh}h^{} + b_y)$$

$$J = -\frac{1}{T} \sum_{t=1}^{T} \sum_{j=1}^{K} y_j^{} \log \hat{y}_j^{}$$

Average with respect to time

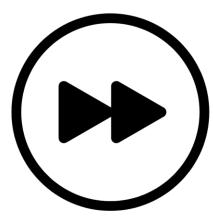
For RNNs the loss function is just an average through time!



### Implementation Note

#### Outline

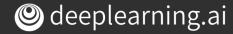
- scan() function in tensorflow
- Computation of forward propagation using abstractions



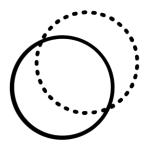
#### tf.scan() function

```
\hat{y}^{< t_1>} \hat{y}^{< t_2>} \qquad \hat{y}^{< T>} def scar(fn, elems, initializer=None, ...):  \begin{array}{c} \text{cur value = initializer} \\ \text{ys = []} \\ \text{for x in elems:} \\ \text{y, cur_value = fn(x, cur_value)} \\ \text{ys.append(y)} \\ \text{return ys, cur_value} \end{array}
```

Frameworks like Tensorflow need this type of abstraction Parallel computations and GPU usage



- Frameworks require abstractions
- tf.scan() mimics RNNs

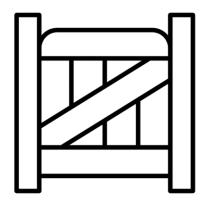




# Gated Recurrent Units

#### Outline

- Gated recurrent unit (GRU) structure
- Comparison between GRUs and vanilla RNNs

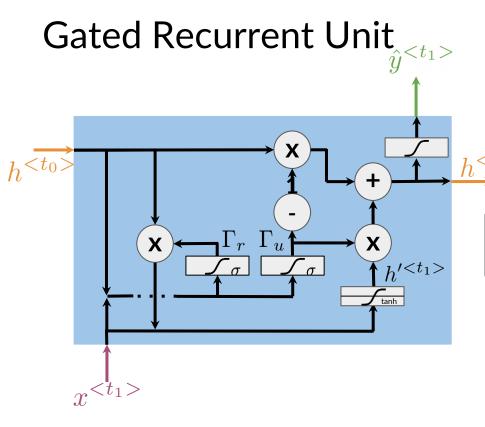


#### **Gated Recurrent Units**

"Ants are really interesting. They are everywhere."

Plural

Relevance and update gates to remember important prior information



Gates to keep/update relevant information in the hidden state

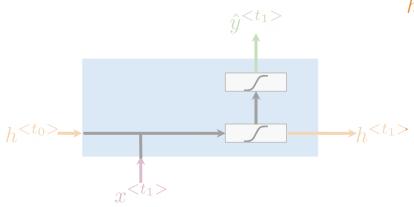
$$\frac{h^{< t_1>}}{\Gamma_u = \sigma(W_r[h^{< t_0>}, x^{< t_1>}] + b_r)} \Gamma_u = \sigma(W_u[h^{< t_0>}, x^{< t_1>}] + b_u)$$

$$h'^{\langle t_1 \rangle} = \tanh(W_h[\Gamma_r * h^{\langle t_0 \rangle}, x^{\langle t_1 \rangle}] + b_h)$$

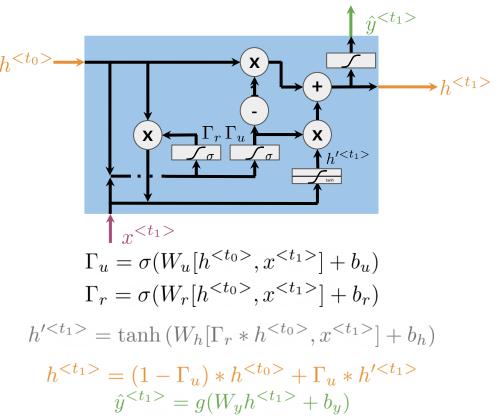
Hidden state candidate

$$h^{\langle t_1 \rangle} = (1 - \Gamma_u) * h^{\langle t_0 \rangle} + \Gamma_u * h'^{\langle t_1 \rangle}$$
$$\hat{y}^{\langle t_1 \rangle} = g(W_y h^{\langle t_1 \rangle} + b_y)$$

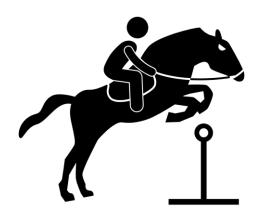
#### Vanilla RNN vs GRUs



$$h^{} = g(W_h[h^{}, x^{}] + b_h)$$
$$\hat{y}^{} = g(W_{yh}h^{} + b_y)$$



- GRUs "decide" how to update the hidden state
- GRUs help preserve important information

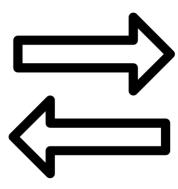




### Deep and Bidirectional RNNs

#### Outline

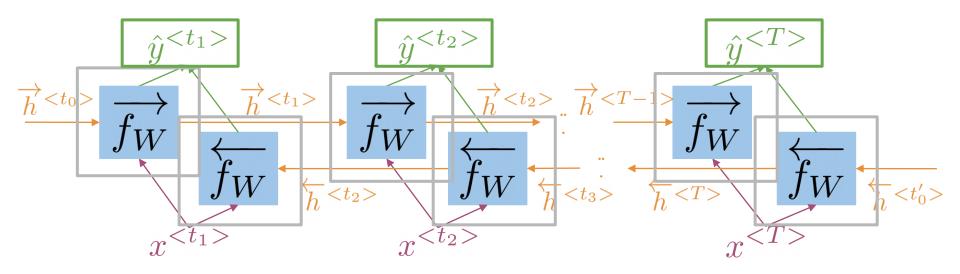
- How bidirectional RNNs propagate information
- Forward propagation in deep RNNs



#### **Bi-directional RNNs**

I was trying really hard to get a hold of \_\_\_\_\_ \_. **Louise**, finally answered when I was about to give up. her him them  $f_{W} \stackrel{h^{< t_{0}>}}{\longrightarrow} f_{W} \stackrel{h^{< t_{1}>}}{\longrightarrow} f_{W}$ 

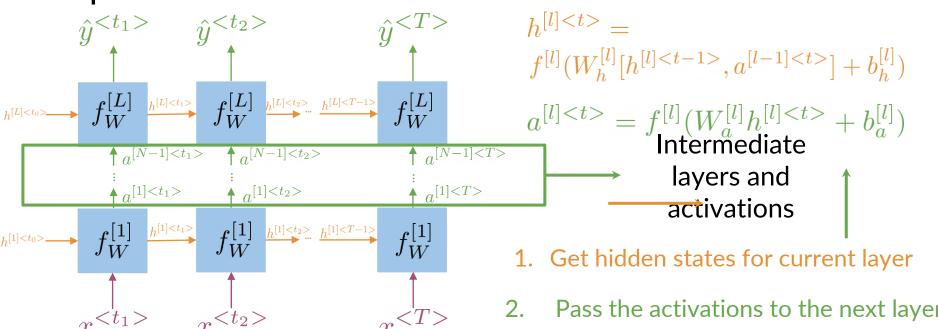
#### **Bi-directional RNNs**



Information flows from the past and from the future

$$\hat{y}^{} = g(W_y^{\text{independently}}, \forall t < t>] + b_y)$$

#### Deep RNNs



- In bidirectional RNNs, the outputs take information from the past and the future
- Deep RNNs have more than one layer, which helps in complex tasks

